

EC centrifugal module - RadiPac

backward curved, single inlet

in cube design

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Nominal data

Type	K3G800-AR08-01	
Motor	M3G200-QA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
State		prelim.
Speed	min ⁻¹	1050
Power input	W	7530
Current draw	A	11.6
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	66.5	56.7	60.7
Efficiency grade N		67.8	58	62
Power input P_{ed}	kW	7.53		
Air flow q_v	m ³ /h	20020		
Pressure increase p_{fs}	Pa	866		
Speed n	min ⁻¹	1055		

Data definition with optimum efficiency. LU-140770
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



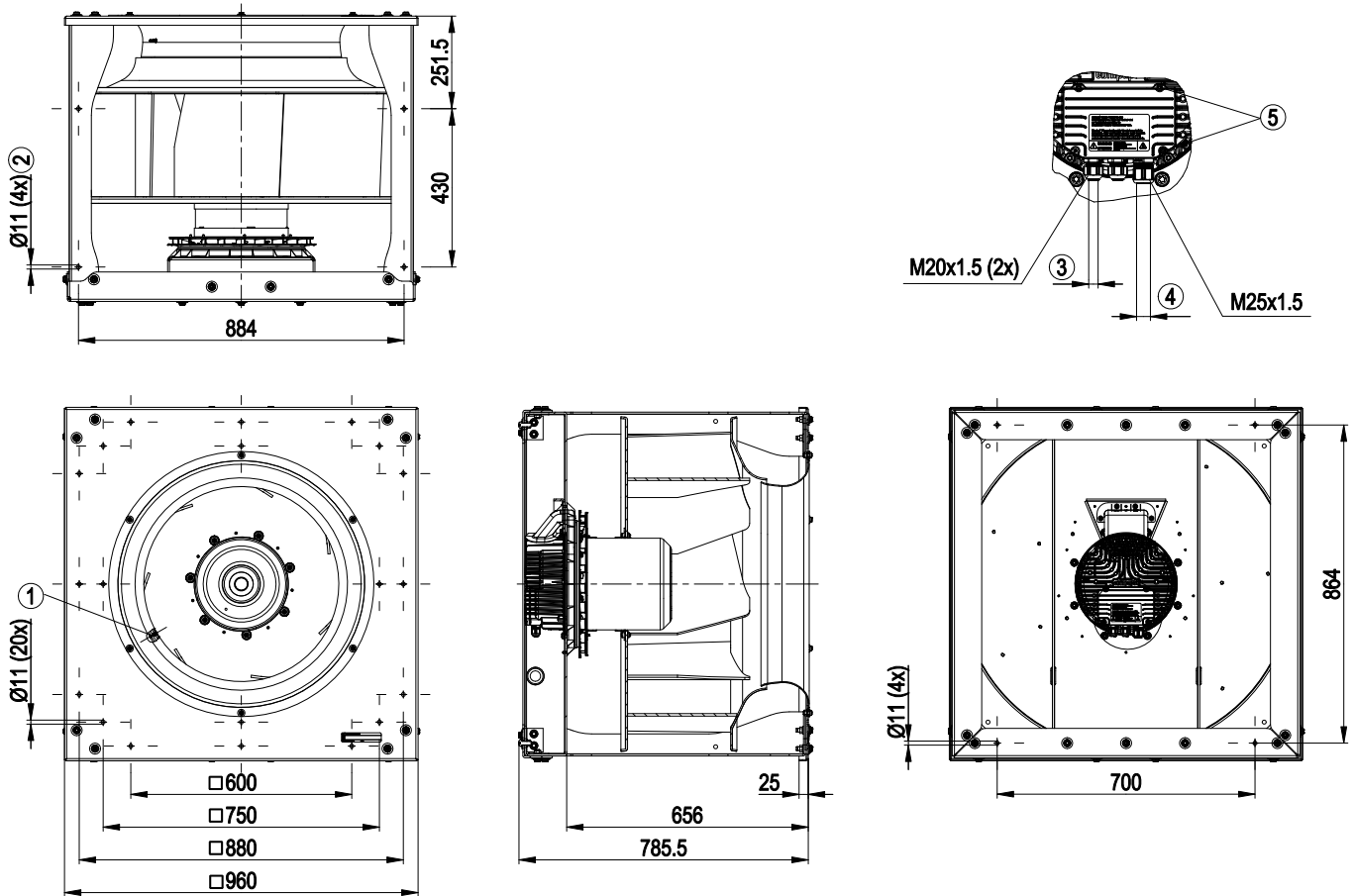
Technical features

Mass	189 kg
Size	800 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of inlet nozzle	Sheet steel, galvanised and plastic-coated in light grey (RAL 7035)
Material of support structure	Sheet steel, galvanised and plastic-coated in light grey (RAL 7035)
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal (only base mounting) or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

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Product drawing



- | | |
|---|--|
| 1 | Inlet nozzle with bleeder connection for pressure relief (k-factor: 695) |
| 2 | Screw-on position for vibration-absorbing elements |
| 3 | Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 4 ± 0.6 Nm |
| 4 | Cable diameter: min. 9 mm, max. 16 mm, tightening torque: 6 ± 0.9 Nm |
| 5 | Tightening torque 3.5 ± 0.5 Nm |

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Connection screen

8	Din 2	RSA	1
9	Din 3	RSB	2
10	GND	GND	3
11	Ain 2 U	Ain 1 U	4
12	+ 20 V	+ 10 V	5
13	Ain 2 I	Ain 1 I	6
14	Aout	Din 1	7

KL 3

1	NO
2	COM
3	NC

KL 2

PE

PE

1	L1
2	L2
3	L3

KL 1

No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer), SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±5/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV



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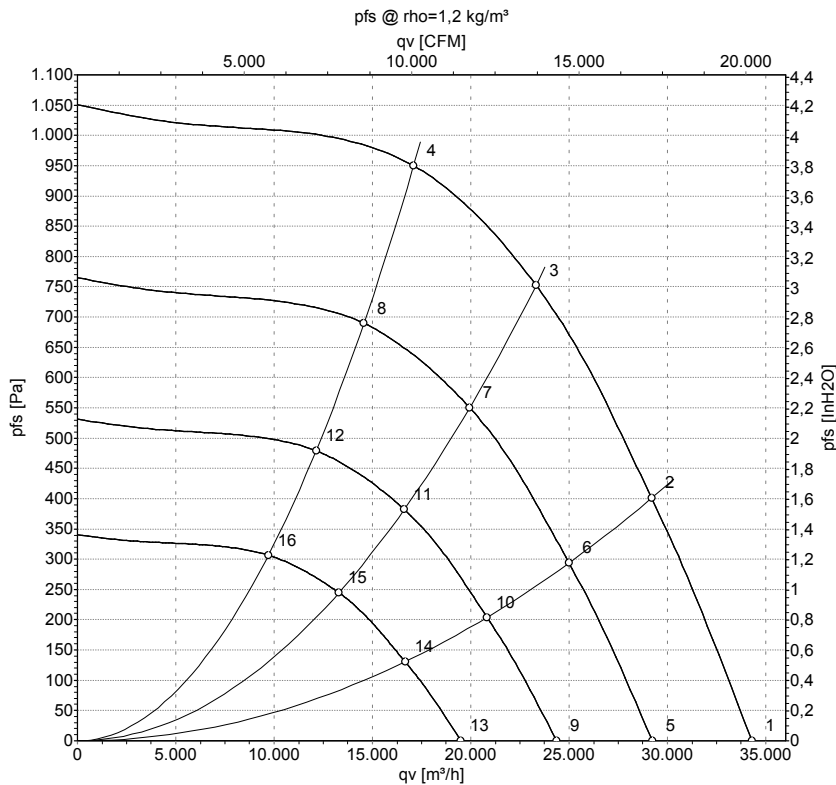
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No.	Conn.	Designation	Function / assignment
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω , parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV



Charts: Air flow 50 Hz



Measurement: LU-140770

Air performance measured as per ISO 5801
Installation category A. For detailed
information on the measuring set-up, please
contact ebm-papst. Suction-side noise
levels: LwA measured as per ISO 13347 /
LpA measured with 1m distance to fan axis.
The values given are valid under the
measuring conditions mentioned above and
may vary according to the actual installation
situation. With any deviation from the
standard set-up, the specific values have to
be checked and reviewed with the unit
installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa
1	400	50	1050	4907	7.58	84	94	98	34280	0
2	400	50	1050	6555	10.10	79	88	93	29185	400
3	400	50	1050	7530	11.60	77	85	90	23310	750
4	400	50	1050	7183	11.02	76	85	89	17085	950
5	400	50	900	3038	4.69	80	90	94	29215	0
6	400	50	900	4115	6.34	75	84	89	24985	294
7	400	50	900	4713	7.22	73	81	86	19935	553
8	400	50	900	4446	6.82	72	80	85	14560	692
9	400	50	750	1758	2.72	76	86	89	24345	0
10	400	50	750	2381	3.67	70	79	84	20820	204
11	400	50	750	2727	4.18	68	77	81	16615	384
12	400	50	750	2573	3.95	68	76	81	12135	481
13	400	50	600	900	1.39	70	80	84	19480	0
14	400	50	600	1219	1.88	64	74	78	16655	131
15	400	50	600	1396	2.14	63	71	75	13290	246
16	400	50	600	1317	2.02	62	70	75	9710	308

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side

qv = Air flow · p_{fs} = Pressure increase